

Problem J

Feeder Robot

Vincent switches his retirement plan from raising horses and goats into raising chickens. He procures N chickens and lays each of them into their own coop (hen house). The coops are placed on a single line numbered sequentially from 1 at the left-most to N at the right-most.

To make his retirement blissful (or at least he thought), Vincent buys a feeder robot. This feeder robot is to be loaded with M pellets and it will distribute them for the chickens to feed on. The feeder robot will move from one coop to an adjacent coop and distribute 1 pellet to each coop it visits. If a coop is visited x times by the robot including the robot's initial position, then it will get x pellets.

However, Vincent has just noticed that he cannot control how the robot moves. Let the robot be in front of coop p . If the robot still has pellets to distribute, it will move to an adjacent coop (coop $p - 1$ or $p + 1$) at random and distributes 1 pellet to that coop. This process repeats until the robot has no more pellets to distribute. Note that if $p = 1$, then the robot will move to coop 2; similarly, if $p = N$, then the robot will move to coop $N - 1$.

Since Vincent dislikes you even though you are his only friend, he challenges you to a problem. The challenge is to count how many possible pellets distributions are there if the robot starts at coop A . A pellets distribution is defined as a tuple $\langle R, S_{1..N} \rangle$ where R is the final position of the robot and S_i is the number of pellets coop i gets. Two distributions are different if and only if the final position of the robot differs or there is a coop that gets a different number of pellets. The robot's movement or the order when the coop gets a pellet does not matter.

Since the output can be quite big, Vincent requires you to give him the non-negative remainder when the output is divided by 998 244 353. Believing that you cannot solve it, Vincent agrees to award you with a hefty reward if you managed to solve his challenge.

For example, let $N = 4$, $M = 3$, and $A = 2$. In this example, there are 3 different pellets distributions.

- $\langle 2, \{1, 2, 0, 0\} \rangle$: The robot ends at coop 2 and the number of pellets each coop gets is $\{1, 2, 0, 0\}$. The robot's movement that causes this distribution is: The robot starts at coop 2 and distributes 1 pellet to coop 2; it moves to coop 1 and distributes 1 pellet to coop 1; it moves to coop 2 and distributes 1 pellet to coop 2. In a simple notation, the robot's movement is $2 \rightarrow 1 \rightarrow 2$.
- $\langle 2, \{0, 2, 1, 0\} \rangle$: The robot ends at coop 2 and the number of pellets each coop gets is $\{0, 2, 1, 0\}$. The robot's movement is $2 \rightarrow 3 \rightarrow 2$.
- $\langle 4, \{0, 1, 1, 1\} \rangle$: The robot ends at coop 4 and the number of pellets each coop gets is $\{0, 1, 1, 1\}$. The robot's movement is $2 \rightarrow 3 \rightarrow 4$.

Input

Input contains three integers $N M A$ ($2 \leq N \leq 100\,000$; $1 \leq M \leq 200\,000$; $1 \leq A \leq N$) representing the number of coops, the number of pellets, and the starting position of the feeder robot, respectively.

Output

Output contains an integer in a line representing the non-negative remainder when the number of different pellets distributions is divided by 998 244 353.

Sample Input #1

```
4 3 2
```

Sample Output #1

```
3
```

Explanation for the sample input/output #1

This is the example from the problem statement.

Sample Input #2

```
3 5 2
```

Sample Output #2

```
3
```

Explanation for the sample input/output #2

There are 3 different pellets distributions in this case.

- $\langle 2, \{2, 3, 0\} \rangle$: The robot ends at coop 2 and the number of pellets each coop gets is $\{2, 3, 0\}$. The robot's movement is $2 \rightarrow 1 \rightarrow 2 \rightarrow 1 \rightarrow 2$.
- $\langle 2, \{0, 3, 2\} \rangle$: The robot ends at coop 2 and the number of pellets each coop gets is $\{0, 3, 2\}$. The robot's movement is $2 \rightarrow 3 \rightarrow 2 \rightarrow 3 \rightarrow 2$.
- $\langle 2, \{1, 3, 1\} \rangle$: The robot ends at coop 2 and the number of pellets each coop gets is $\{1, 3, 1\}$. The robot's movement is $2 \rightarrow 1 \rightarrow 2 \rightarrow 3 \rightarrow 2$ or $2 \rightarrow 3 \rightarrow 2 \rightarrow 1 \rightarrow 2$; both of them give the same distribution, i.e. the robot ends at the same coop and each coop gets the same number of pellets in both distributions.

Sample Input #3

```
3 6 2
```

Sample Output #3

```
6
```

Explanation for the sample input/output #3

There are 6 different pellets distributions in this case: $\langle 1, \{3, 3, 0\} \rangle$, $\langle 1, \{2, 3, 1\} \rangle$, $\langle 3, \{2, 3, 1\} \rangle$, $\langle 1, \{1, 3, 2\} \rangle$, $\langle 3, \{1, 3, 2\} \rangle$, and $\langle 3, \{0, 3, 3\} \rangle$.